



Figure 1: The conditional densities and the decision region.

# Communication and Detection Theory

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## Model Answers to Exercise 10 of May 2, 2017

<http://www.isi.ee.ethz.ch/teaching/courses/cdt>

### Problem 1

### *Hypothesis Testing*

- (i) The two conditional probability densities can be computed using the rule relating the density of the transformed random variable to the density of the random variable (19.7):

$$f_{Y|H=0}(y) = \frac{1}{2}e^{-|y-a|}, \quad y \in \mathbb{R},$$

$$f_{Y|H=1}(y) = \frac{1}{2}e^{-|y+a|}, \quad y \in \mathbb{R}.$$

The two densities are depicted in Figure 1.

(ii) The likelihood ratio is

$$\begin{aligned} \text{LR}(y) &= \frac{f_{Y|H=0}(y)}{f_{Y|H=1}(y)} \\ &= e^{|y+a|-|y-a|} \\ &= \begin{cases} e^{-2a} & y \leq -a, \\ e^{2y} & -a < y < a, \\ e^{2a} & y \geq a. \end{cases} \end{aligned}$$

Since the hypotheses are equally likely, we guess “ $H = 0$ ” if  $\text{LR}(y) > 1$  and guess “ $H = 1$ ” if  $\text{LR}(y) \leq 1$ . Thus, an optimal decision rule is to guess “ $H = 0$ ” if  $y > 0$ , and to guess “ $H = 1$ ” if  $y \leq 0$ . This decision rule is depicted in Figure 1.

(iii) Let  $p^*(\text{error})$  denote the optimal probability of error. Then,

$$\begin{aligned} p^*(\text{error}) &= p^*(\text{error}|H = 0) \Pr[H = 0] + p^*(\text{error}|H = 1) \Pr[H = 1] \\ &= \frac{1}{4} \int_{-\infty}^0 e^{-|y-a|} dy + \frac{1}{4} \int_0^{\infty} e^{-|y+a|} dy \\ &= \frac{1}{4} e^{(y-a)} \Big|_{-\infty}^0 - \frac{1}{4} e^{-(y+a)} \Big|_0^{\infty} \\ &= \frac{1}{2} e^{-a}. \end{aligned}$$

(iv) Applying the Bhattacharyya bound we get

$$\begin{aligned} p^*(\text{error}) &\leq \frac{1}{2} \int_{-\infty}^{\infty} \sqrt{\frac{1}{4} e^{-|y-a|-|y+a|}} dy \\ &= \frac{1}{4} \left( \int_{-\infty}^{-a} e^y dy + \int_{-a}^a e^{-a} dy + \int_a^{\infty} e^{-y} dy \right) \\ &= \frac{1}{4} (e^{-a} + 2ae^{-a} + e^{-a}) \\ &= \left( \frac{a+1}{2} \right) e^{-a}. \end{aligned}$$

As expected, for all values of  $a \geq 0$  the Bhattacharyya bound is indeed an upper bound on the exact probability error computed in Part (iii).

## Problem 2

## Binary Hypothesis Testing

(i) Since  $f_{Y|H=1}(\cdot)$  integrates to one,

$$\begin{aligned} 1 &= \int_{-\infty}^{\infty} f_{Y|H=1}(y) dy \\ &= \int_0^{\infty} \beta e^{-\frac{y^2}{2}} dy \\ &= \frac{1}{2} \int_{-\infty}^{\infty} \beta e^{-\frac{y^2}{2}} dy \\ &= \frac{1}{2} \beta \sqrt{2\pi} \\ &= \beta \sqrt{\frac{\pi}{2}}. \end{aligned}$$

Consequently,  $\beta = \sqrt{\frac{2}{\pi}}$ .

(ii) An optimal rule is

$$\begin{aligned} \text{guess "H = 0"} &\iff \left( \frac{\pi_0 f_{Y|H=0}(y)}{\pi_1 f_{Y|H=1}(y)} > 1 \right) \\ &\iff \left( \frac{e^{-y}}{e^{-\frac{y^2}{2}}} > \frac{\pi_1}{\pi_0} \sqrt{\frac{2}{\pi}} \right) \\ &\iff \left( \frac{y^2}{2} - y - \ln \left( \sqrt{\frac{2}{\pi}} \frac{\pi_1}{\pi_0} \right) > 0 \right) \\ &\iff \left( \frac{y^2}{2} - y - \gamma > 0 \right), \end{aligned}$$

where we have defined

$$\gamma = \ln \left( \sqrt{\frac{2}{\pi}} \frac{\pi_1}{\pi_0} \right).$$

The roots of the polynomial  $y^2/2 - y - \gamma$  are

$$y_{1,2} = 1 \pm \sqrt{1 + 2\gamma}.$$

Depending on the value of  $\gamma$  (or the ratio  $\pi_1/\pi_0$ ) we have to distinguish different cases:

- If  $\gamma > 0$  (or  $\pi_1/\pi_0 > \sqrt{\pi/2}$ ) the quadratic equation has exactly one *positive* real solution:  $y_1 = 1 + \sqrt{1 + 2\gamma}$ . Hence, we decide  $H = 0$  only if  $y > y_1$ .
- If  $-1/2 < \gamma < 0$  (or  $\sqrt{\pi/2}e^{-1/2} < \pi_1/\pi_0 < \sqrt{\pi/2}$ ) the quadratic equation has two *positive* real solutions:  $y_1 = 1 + \sqrt{1 + 2\gamma}$  and  $y_2 = 1 - \sqrt{1 + 2\gamma}$ . Hence, we decide  $H = 0$  only if  $0 < y < y_2$  or  $y_1 < y$ .
- Finally, if  $\gamma < -1/2$  (or  $\pi_1/\pi_0 < \sqrt{\pi/2}e^{-1/2}$ ) the quadratic solution does not have any real solution. Hence, we decide  $H = 0$  for every  $y$ .

(iii) As above we have to distinguish the three different cases:

- $\gamma > 0$  (or  $\pi_1/\pi_0 > \sqrt{\pi/2}$ ): The probability of error in this case is

$$\Pr(\text{error}|H = 0) = \int_0^{y_1} f_{Y|H=0}(y) dy = 1 - e^{-y_1},$$

where  $y_1 = 1 + \sqrt{1 + 2\gamma}$ .

- $-1/2 < \gamma < 0$  (or  $\sqrt{\pi/2}e^{-1/2} < \pi_1/\pi_0 < \sqrt{\pi/2}$ ): The probability of error in this case is

$$\Pr(\text{error}|H = 0) = \int_{y_1}^{y_2} f_{Y|H=0}(y) dy = e^{-y_2} - e^{-y_1},$$

where  $y_1$  as above and  $y_2 = 1 - \sqrt{1 + 2\gamma}$ .

- $\gamma < -1/2$  (or  $\pi_1/\pi_0 < \sqrt{\pi/2}e^{-1/2}$ ): In this case we always decide  $H = 0$ . Thus, the probability of error is

$$\Pr(\text{error}|H = 0) = 0.$$

### Problem 3

### *Hypothesis Testing with a Random Parameter*

- (i) If we observe that  $A = 2$ , then the problem reduces to guessing  $X$  based on  $X + Z_2$ , where  $Z_2 \sim \mathcal{N}(0, 4\sigma^2)$ . An optimal guessing rule is in this case to guess “ $X = -1$ ” if  $Y < 0$  and “ $X = +1$ ” if  $Y > 0$ . If we observe that  $A = 3$ , then the problem reduces to guessing  $X$  based on  $X + Z_3$ , where  $Z_3 \sim \mathcal{N}(0, 9\sigma^2)$  with the same optimal rule. Thus, irrespective of the observed value of  $A$ , it is optimal to guess “ $X = -1$ ” if  $Y < 0$  and to guess “ $X = +1$ ” if  $Y > 0$ .
- (ii) The above rule remains optimal even if we do not observe  $A$ , because its implementation does not require knowledge of  $A$ . When  $A$  is not observed we can thus do as well as if  $A$  were observed.

#### Problem 4

#### *Artifacts of Suboptimality*

- (i) For Alice’s guessing rule

$$\begin{aligned} \Pr(\text{error}) &= \pi_0 \Pr[Y \leq 2 \mid H = 0] + \pi_1 \Pr[Y > 2 \mid H = 1] \\ &= \frac{1}{2} \left( 1 - \mathcal{Q}\left(\frac{1}{\sigma}\right) + \mathcal{Q}\left(\frac{3}{\sigma}\right) \right). \end{aligned}$$

- (ii) As  $\sigma \rightarrow \infty$  we get  $\Pr(\text{error}) \rightarrow \frac{1}{2}$  and as  $\sigma \rightarrow 0$  we get  $\Pr(\text{error}) \rightarrow \frac{1}{2}$ . But for  $\sigma = 1$  we have  $\Pr(\text{error}) < \frac{1}{2}$ . Thus,  $\Pr(\text{error})$  is not monotonically nondecreasing in  $\sigma^2$ .
- (iii) An optimal guessing rule is to guess “ $H = 0$ ” if  $Y > 0$  and to guess “ $H = 1$ ” if  $Y \leq 0$ . The associated minimal probability of decoding error is

$$\begin{aligned} p^*(\text{error}) &= \frac{1}{2} \Pr[Y \leq 0 \mid H = 0] + \frac{1}{2} \Pr[Y > 0 \mid H = 1] \\ &= \mathcal{Q}\left(\frac{1}{\sigma}\right). \end{aligned}$$

Since this is in general not equal to the probability of error of Alice’s rule, Alice’s rule does not minimize the probability of error.

- (iv) For  $\sigma = 0.1 \Rightarrow \Pr(\text{error}) \approx 0.5000$ .  
 For  $\sigma = 2 \Rightarrow \Pr(\text{error}) \approx 0.2583$ .  
 Thus if  $\sigma = 0.1$ , then guessing  $H$  based on  $Y + Z$  where  $Z \sim \mathcal{N}(0, 1.9)$ ,  $Z \perp\!\!\!\perp Y$ , will reduce the error probability by almost 0.25.